

An Exact Algorithm for the Linear Tape Scheduling Problem

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Tape usage today



(or 11  football fields)

≈ 20TB on 1000s × 1km read at 10m/s – 100s MB/s

<https://commons.wikimedia.org/wiki/File:LT02-cart-wo-top-shell.jpg>
https://commons.wikimedia.org/wiki/File:Usain_Bolt_Rio_100m_final_2016i-cr.jpg



Primordial for HTC (High Throughput Computing)

e.g.,

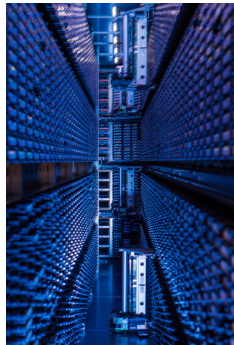


(100s PB)

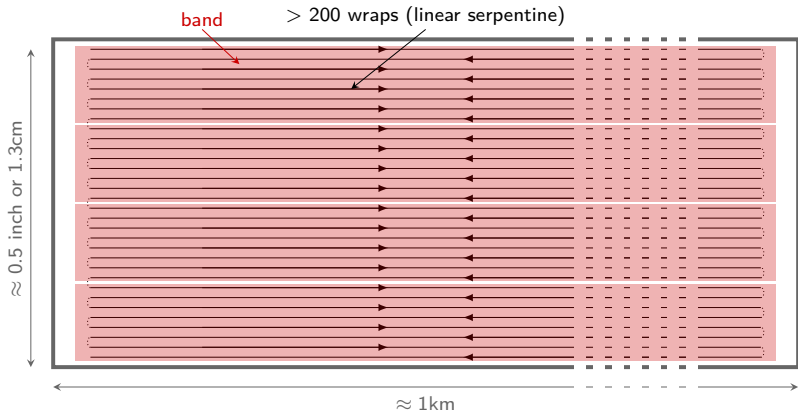
also: media companies, cloud archive. . .

😊 Impressive technology improvements
 density: + 30% / year (vs HDD: + 8%)

😞 High latency (mount, load, position → few mn)
 Adapted for Write Once Read Many

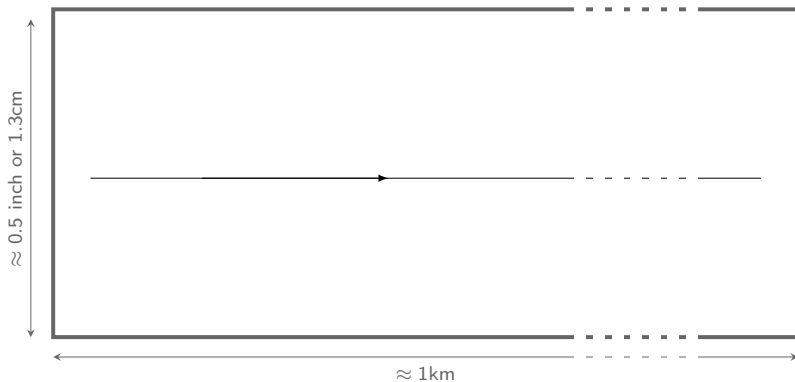


Overview of a tape



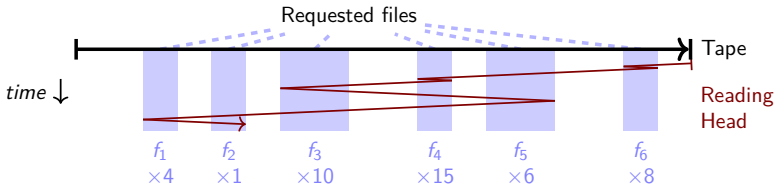
wrap = dozens of tracks read / written simultaneously by parallel heads

Overview of our tape model



Linear Tape Scheduling Problem

[CardonhaReal'16]



Assumptions:

- ▶ files are read left-to-right
- ▶ start on the right
- ▶ constant speed

Input:

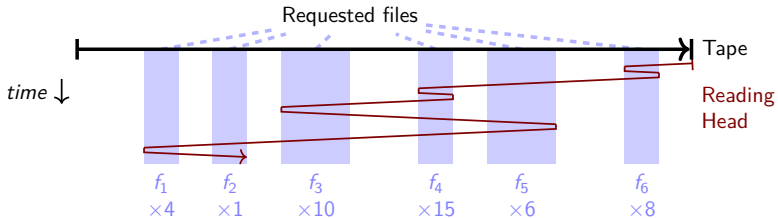
- ▶ tape of n_f consecutive files
- ▶ n file requests (44 here)
- ▶ n_{req} distinct files requested (6)

Objective: average service time

Motivation: lack of fundamental theoretical results, models local files

Linear Tape Scheduling Problem

[CardonhaReal'16]



Assumptions:

- ▶ files are read left-to-right
- ▶ start on the right
- ▶ constant speed
- ▶ [new] U-turn penalty U

Input:

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Related to the Linear Tape Scheduling Problem



Travelling Salesperson Problem (TSP)

- ▶ super-famous NP-hard problem
- ▶ recent $(1.5 - 10^{-36})$ -approximation [KarlinKleinGaran'21]
- ▶ 😞 minimizes makespan, trivial on the real line

Minimum Latency Problem / TRP (Repair) - variant

- ▶ 😊 minimize average service time $\in P$ on the real line
- ▶ delays to repair a node: complexity open



Dial-a-ride variant on the real line

- ▶ \approx LTSP but with overlapping files in both directions
→ NP-hard

Tapes except LTSP: 2 specific experimental papers in the 90's

Structural results

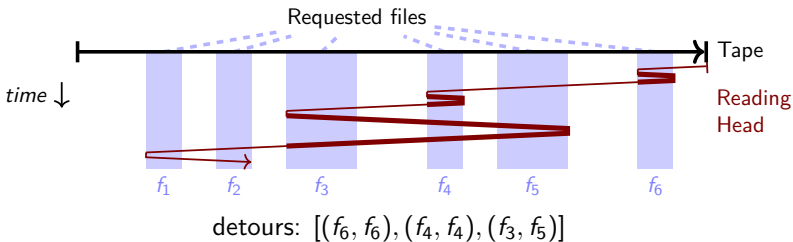
Any optimal solution

- ▶ after reaching $\ell(f_1)$, go straight to the rightmost unread request
- ▶ can be described by a set of **detours** done before

Definition (Detours)

A solution includes the **detour** (a,b) with $a \leq b$ if:

- ▶ the 1st time the head reaches $\ell(a)$, go straight to $r(b)$, back to $\ell(a)$



Structural results

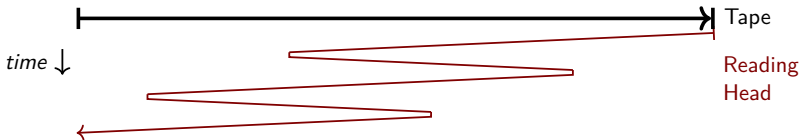
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Lemma: detours never partially overlap (*strictly laminar*)

Structural results

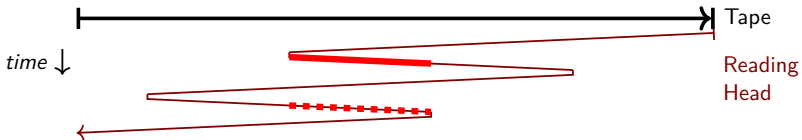
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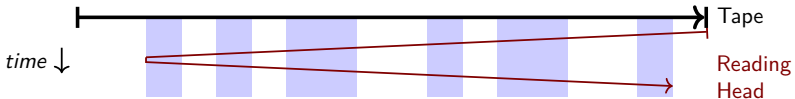


Lemma: detours never partially overlap (*strictly laminar*)

Naive algorithms

NO DETOUR: go to the leftmost request, then to the rightmost

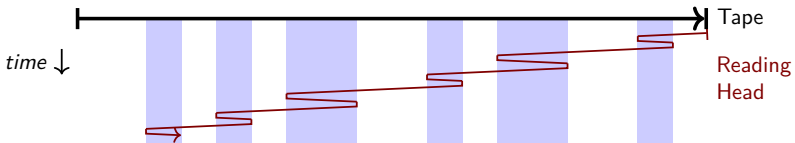
can be arbitrarily bad (place urgent requests on the right)



GS (Greedy Schedule): do all atomic detours, *i.e.*, $\{(f_i, f_i)\}_{\forall i}$

Lemma [CardonhaReal'16]: **GS** is a 3-approximation if $U = 0$

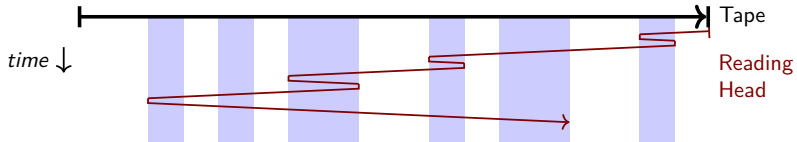
Proof: does ≤ 3 times the optimal distance before reading each request



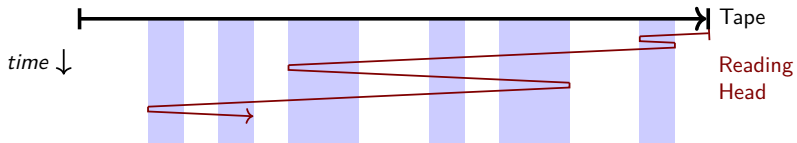
Heuristic improvements

[CardonhaCiréReal'18]

FGS (Filtered): remove detrimental atomic detours in $O(n_{req}^2)$



NFGS (Non-atomic): greedily add long detours if currently beneficial. Make one pass from left to right. Complexity in $O(n_{req}^3)$



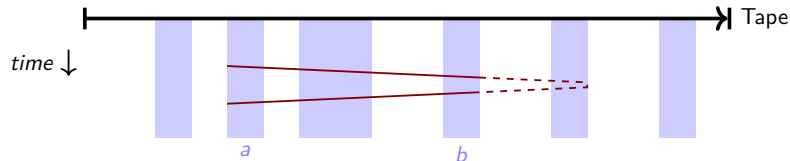
Dynamic Program DP: overview

Each cell: three parameters $T[a, b, n_{skip}]$

► compute the best strategy from $r(\mathbf{b})$ to $\ell(\mathbf{a})$ assuming:

- 1 there is a detour (\mathbf{a}, f) for some $f \geq \mathbf{b}$,
- 2 there is no detour (f_1, f_2) such that $\mathbf{a} < f_1 < \mathbf{b} < f_2$,
- 3 when reaching $r(\mathbf{b})$, exactly n_{skip} requests have been skipped.

⇒ value \approx cost contribution from 'first $r(b)$ ' to ' $r(b)$ after reading a '



Subtleties: \forall request on f , do not count the cost $m \rightarrow \ell(f) \rightarrow r(f)$
if f is read after b , remove one U (counted before)

Dynamic Program DP: overview

Each cell: three parameters $T[a, b, p, u]$



More dynamic programs

Theorem

DP solves *LTSP* exactly in time $O(n \cdot n_{req}^3)$.

LOGDP(λ): **DP** restricted to detours spanning $\lambda \log n_{req}$ requested files

Reduced complexity in $O(\lambda^2 \cdot n_{req} \cdot n \cdot \log^2(n_{req}))$, tested with $\lambda \in \{1, 5\}$

SIMPLEDP: **DP** forbidding intertwined (*i.e.*, overlapping) detours

Reduced complexity in $O(n \cdot n_{req}^2)$, better theoretical guarantees

Simulations: overview

Dataset: 2 weeks at CC-IN2P3

- ▶ 169 tapes, > 3M files
- ▶ focus on reading operations
- ▶ filtering steps, data processing (e.g., merge reads on aggregates)
- ▶ median data: 150 files requested, 3k requests, 50% file size variation

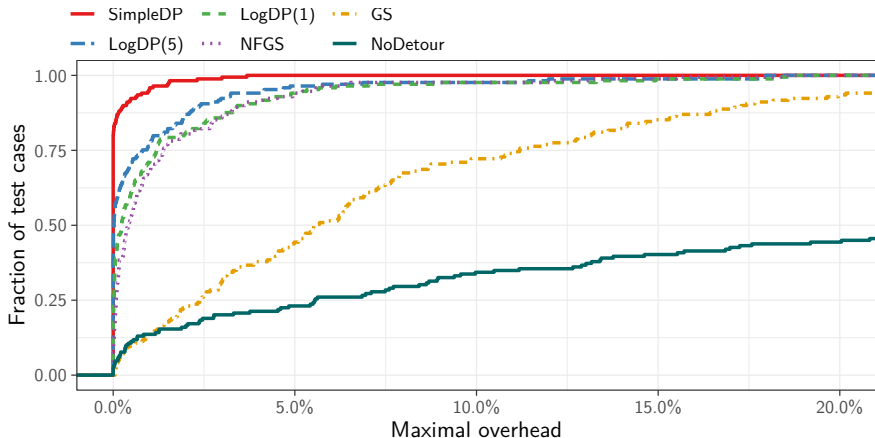
Code + dataset (with statistical descriptions) available online

Experimental methodology

- ▶ vary U
- ▶ median timings (seconds, on a compiled Python program):

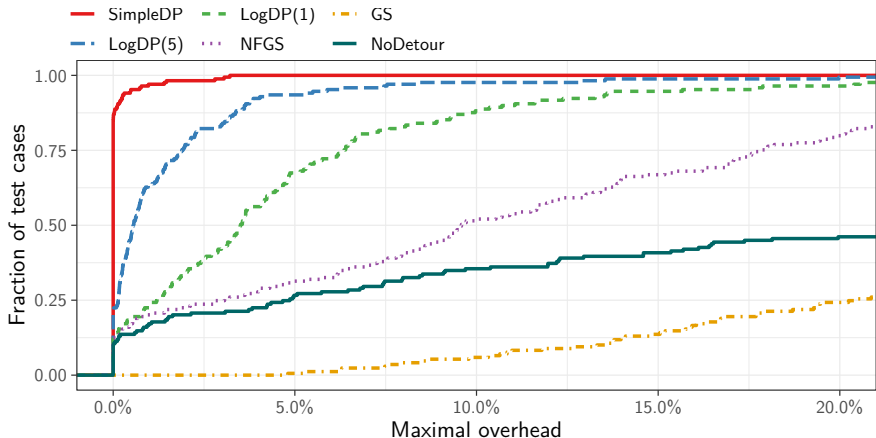
FGS	NFGS	LOGDP(1)	SIMPLEDP	LOGDP(5)	DP
< 0.1	1	2	3	7	30

Simulation results, $U = 0$



Performance profile: best is top-left (most instances with low overhead vs OPT)

Simulation results, $U = \text{file}$



Performance profile: best is top-left (most instances with low overhead vs OPT)

Conclusion



<https://commons.wikimedia.org/wiki/File:LT02-cart-wo-top-shell.jpg>

General: tapes are past & future

- ▶ tapes stay primordial in some fields but neglected by CS research
- ▶ fundamental problems are still open

On LTSP

- ▶ high-multiplicity variant remains open
- ▶ huge gap between theoretically studied models and practical heuristics

Perspectives on other tape-related topics

- ▶ multi-tape requests: optimize waiting queues
- ▶ optimize tape / disk storage ratio

